

Robotics and Digital Agriculture

Salah Sukkarieh

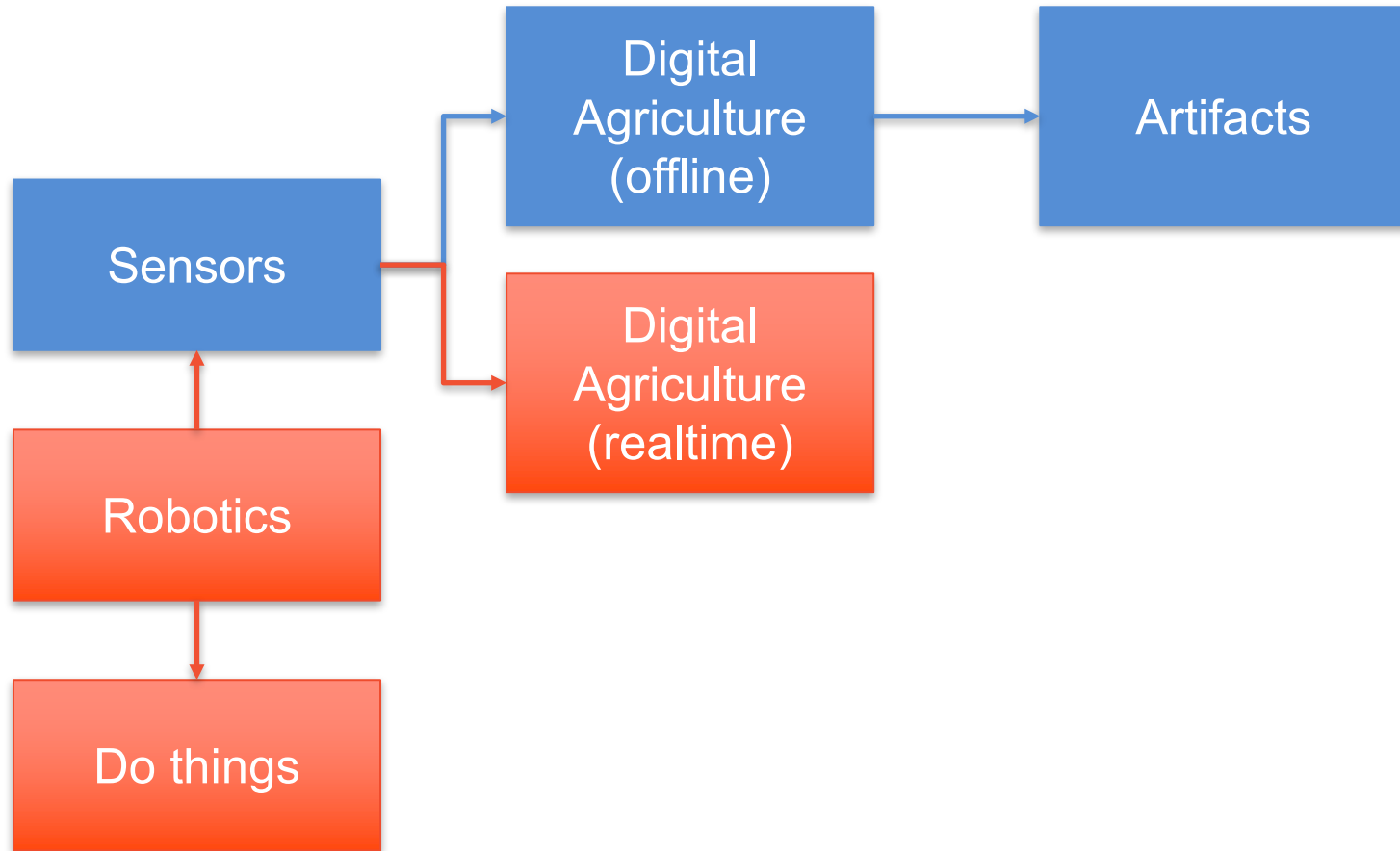
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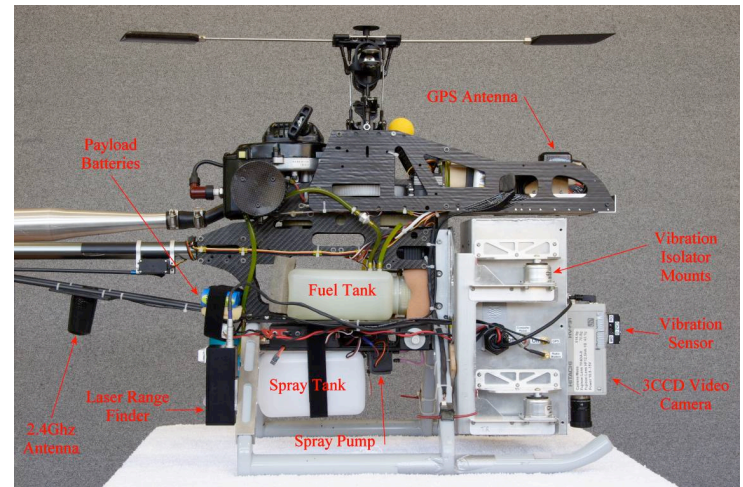
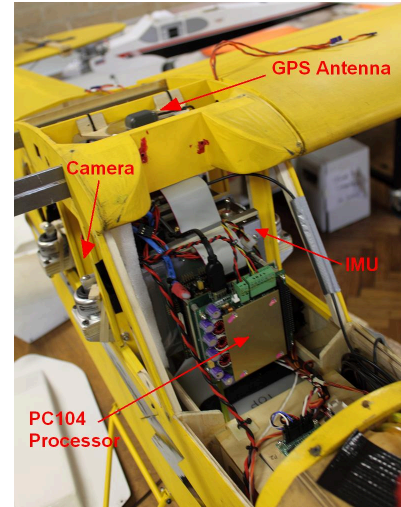
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Field Robotics**

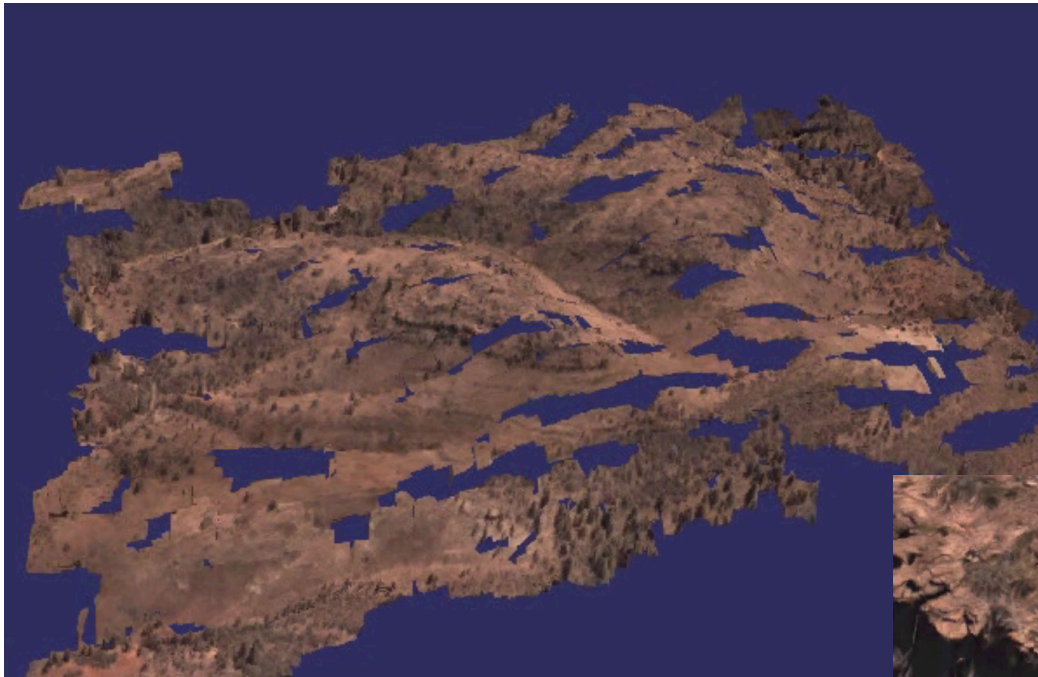
A very basic description...



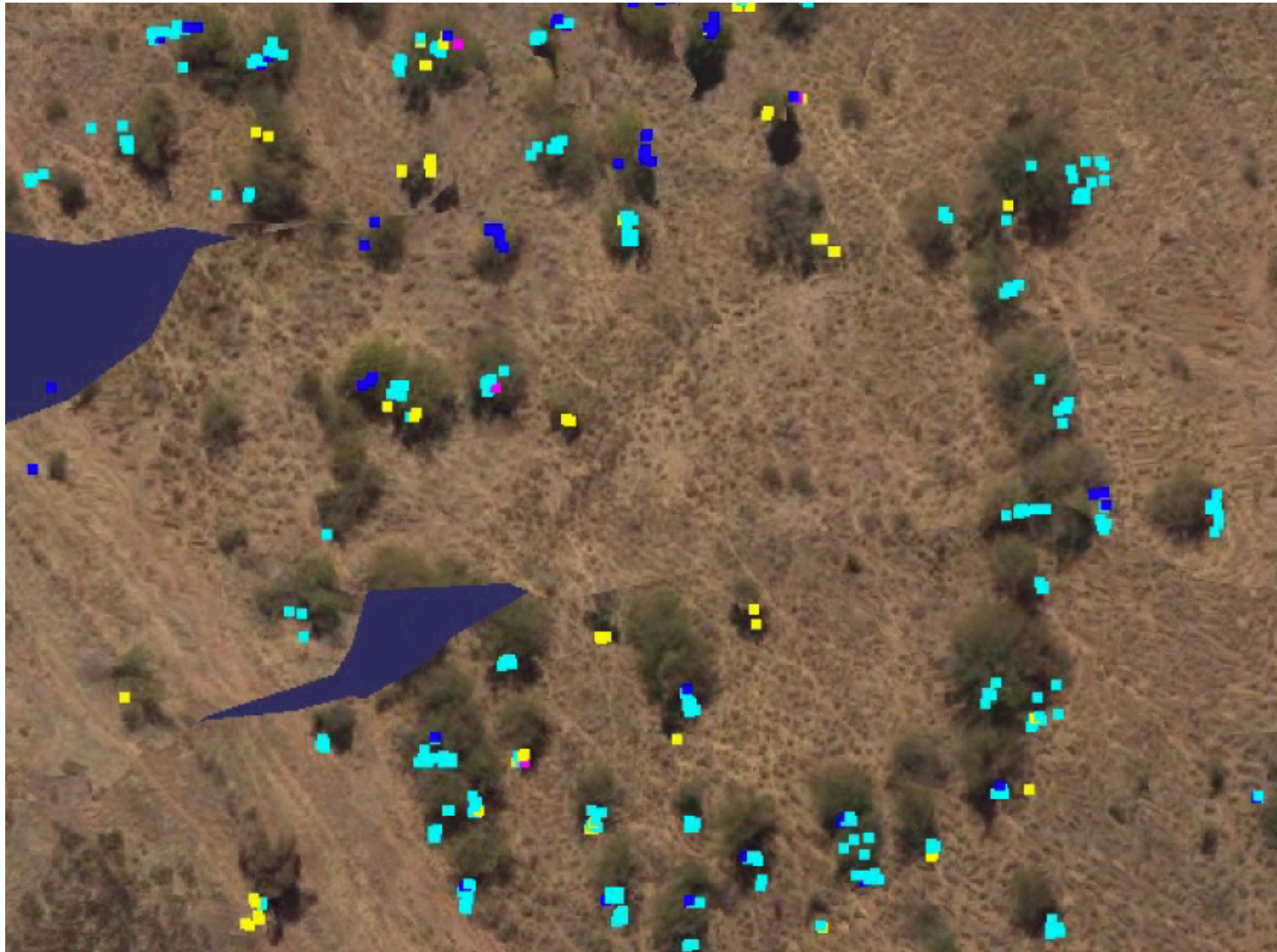
2006: Large-Scale Autonomous Remote Surveillance



2008-2010: High Precision Data Fusion and Mapping



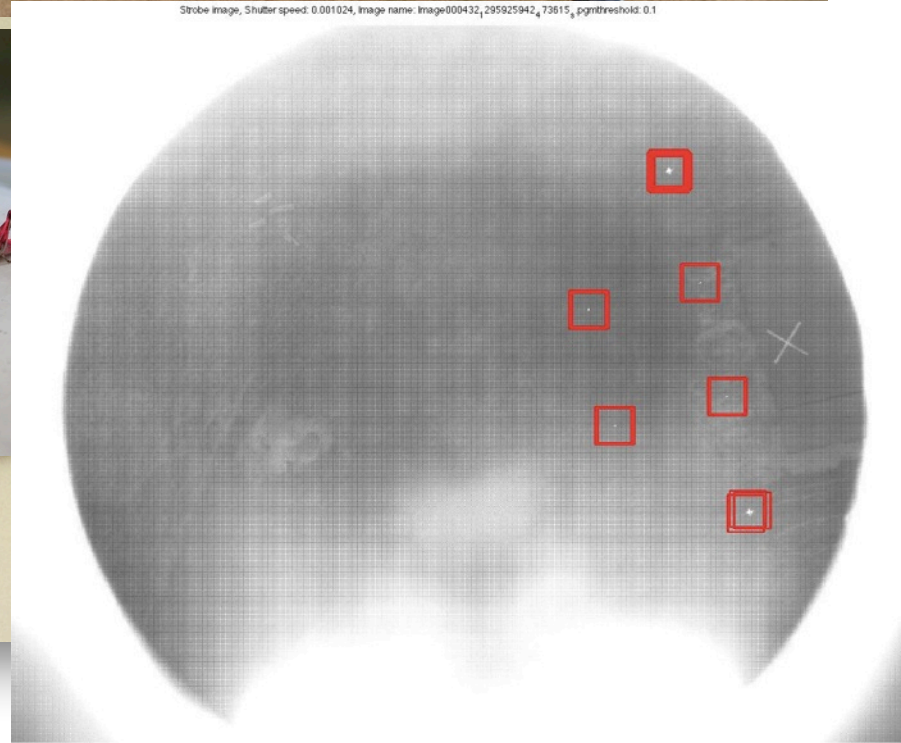
2008-2010: Automated Machine Learning Algorithms



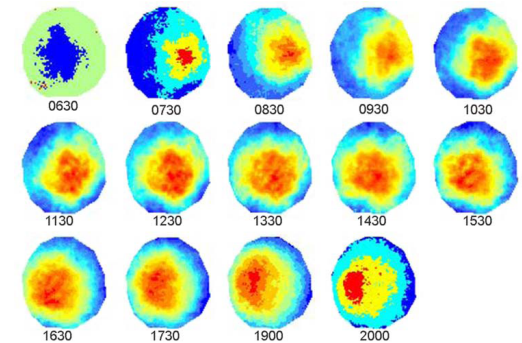
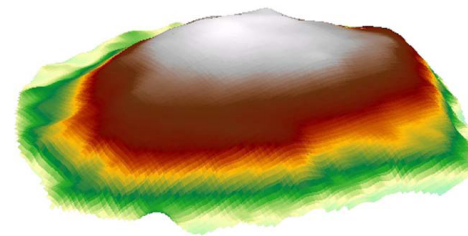
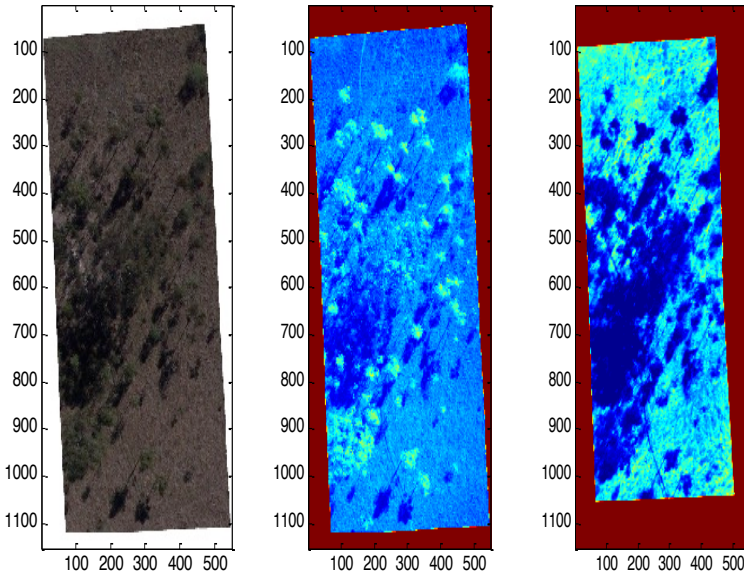
2011: Precision Pest Tracking / Monitoring



Strobe image, Shutter speed: 0.001024, Image name: Image000432_295925942_73615_pgrntreshold: 0.1

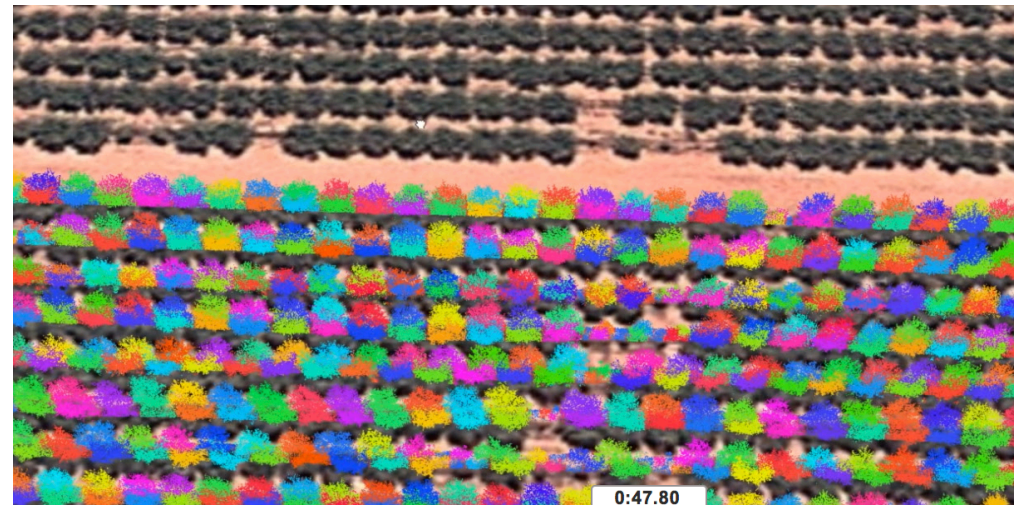
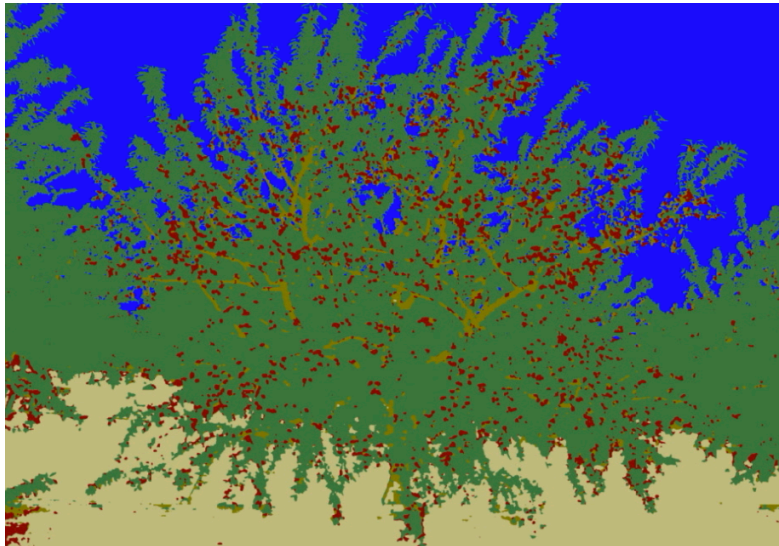
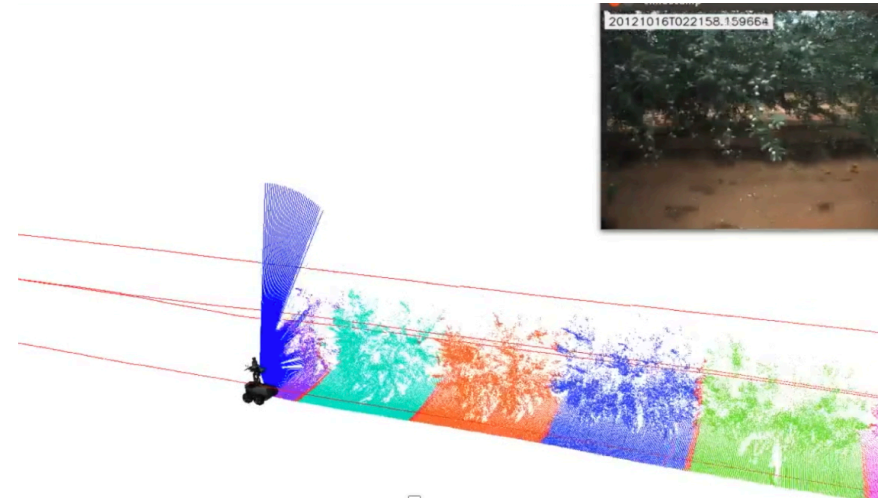


2015: Large-Scale Multi-Environment Mapping and Classification



Vogt et al, Dynamic Thermal Structure of Imported Fire Ant Mounds, Journal of Insect Science Vol.8

2015: Almond Trials



2016: Multi spatial & temporal resolution

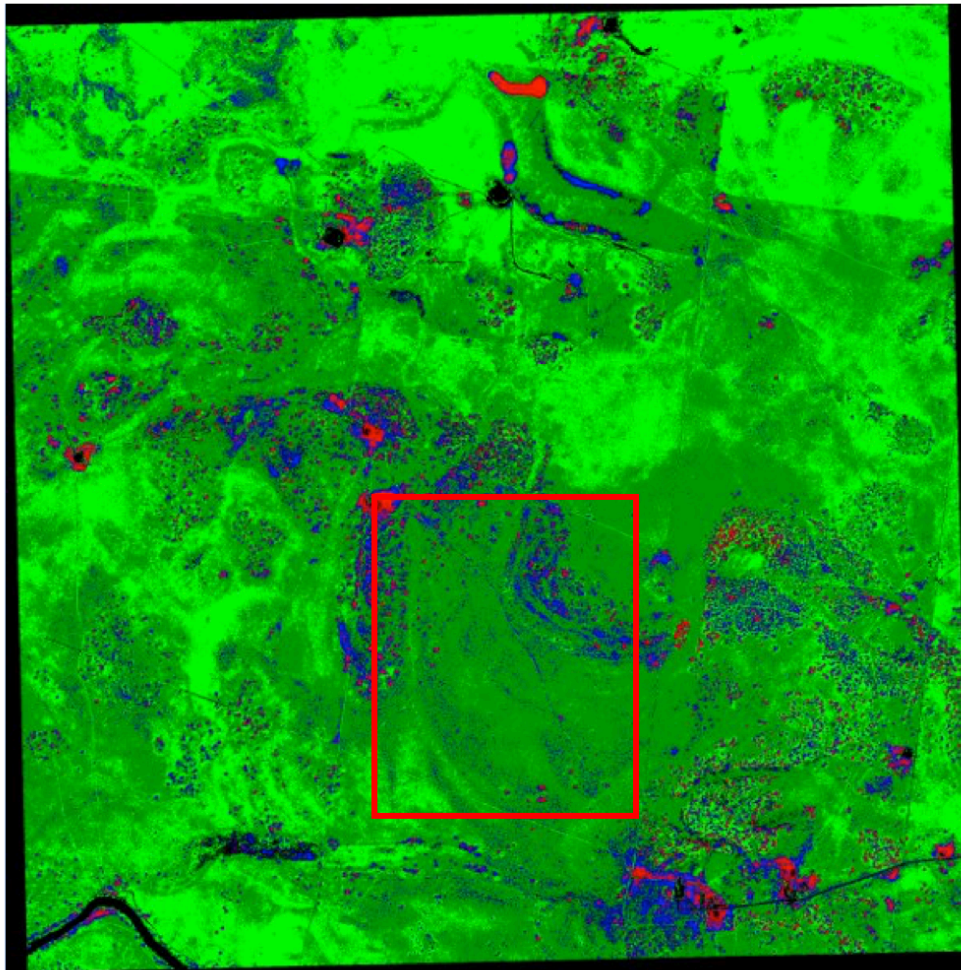
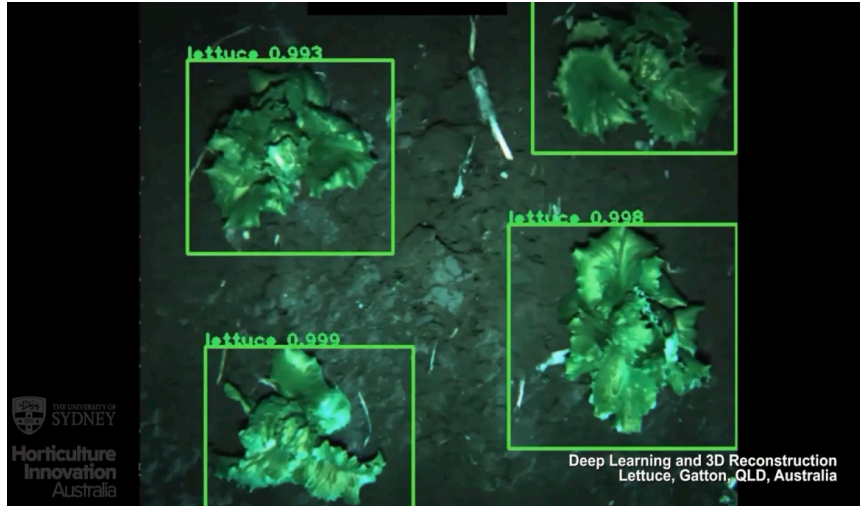


Figure 31: Results of the SAM classification of World View 2 data across the entire satellite data set. The classes are: soil (yellow), mimosa and boxthorn (blue), eucalypt (red) and other vegetation (green). The UAV survey area is outlined in red.

2017: Vegetable Row Crops



2017: Vegetable Row Crops



2017: Small Holder farm trial



Farmhand travels down row crop collecting data

Future: Co-Learning: merging structured and unstructured data and decisions

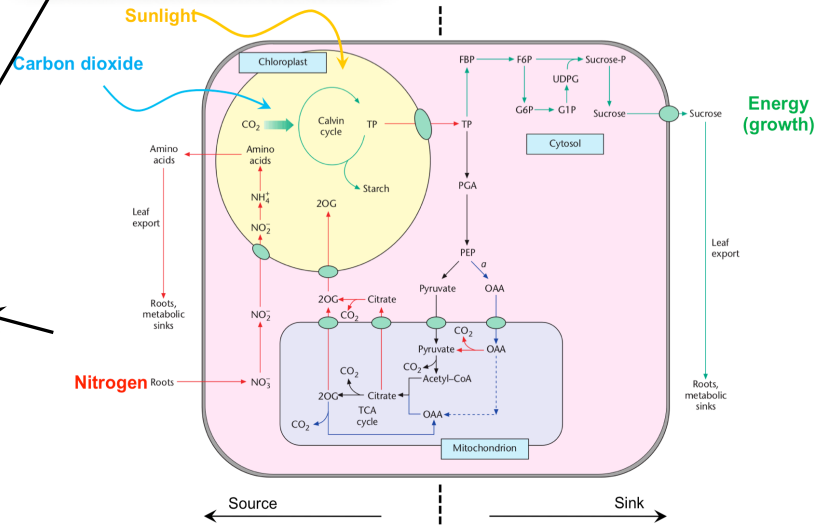
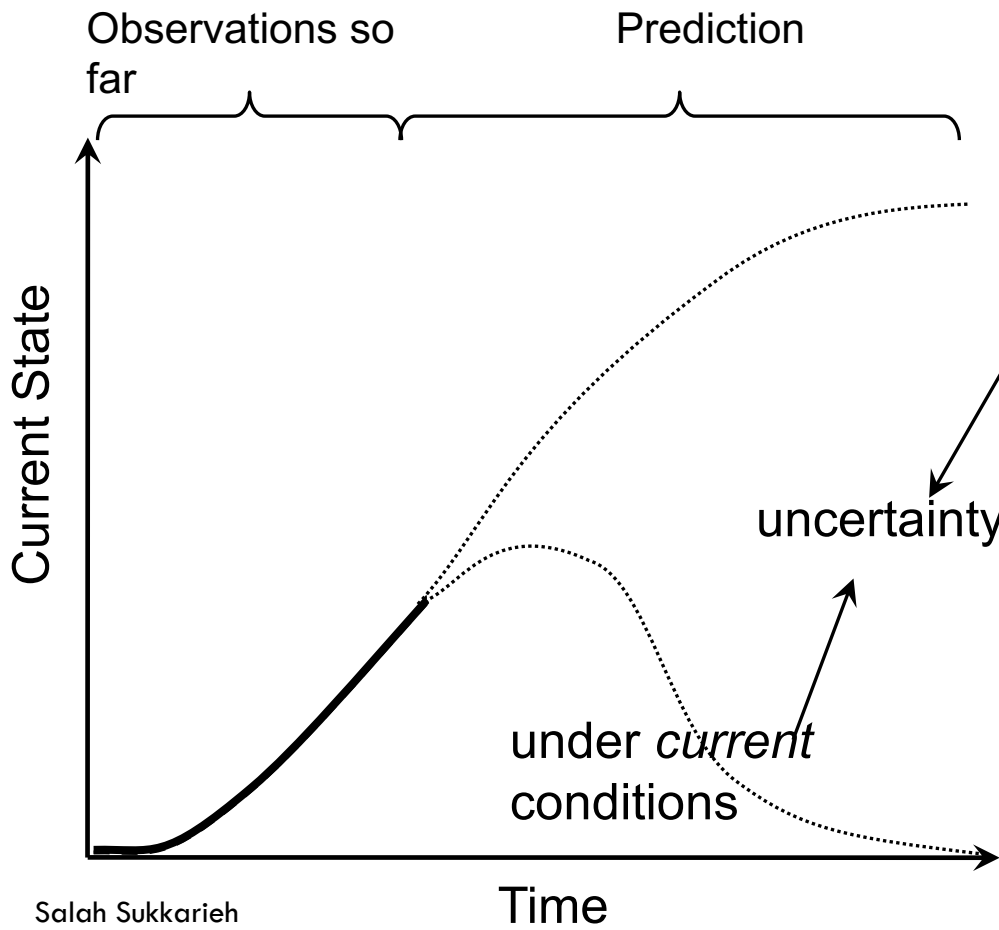


Image from: Foyer, Christine H., and Matthew J. Paul. "Source-sink relationships." eLS (2001).

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