# Liouville theorem for surfaces translating by sub-affine-critical powers of Gauss curvature 

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## POSTECH

Asia-Pacific Analysis and PDEs Seminar

## Liouville theorem

Let $u(x)$ be an entire harmonic $(\Delta u=0)$ function on $\mathbb{R}^{n}$.

- Bounded (one-side), then $u=$ constant
- If $|u(x)| \leq C(1+|x|)^{m}$, then $u=$ harmonic polynomials of order $\leq m$

Examples on $\mathbb{R}^{2}$,

$$
\begin{array}{cl}
u=1, & r \cos \theta=x, \quad r^{2} \cos 2 \theta=x^{2}-y^{2} \\
& r^{n} \cos (n \theta), \quad r^{n} \sin (n \theta)
\end{array}
$$

## Bernstein problem

Let $x_{n+1}=u(x)$ be an entire minimal hypersurface

$$
\operatorname{div}\left(\frac{D u}{\left(1+|D u|^{2}\right)^{1 / 2}}\right)=0 \text { on } \mathbb{R}^{n}
$$

- If $n<8$, then $u$ must be a linear function Bernstein, Fleming, De Giorgi, Almgren, J. Simons, Bombieri-De Giorgi-Giusti (counter example when $n=8$ )


## Fleming '62 $n=2$

If $x_{n+1}=u(x)$ is non-flat entire minimal, as $\lambda \rightarrow \infty$

$$
x_{n+1}=\lambda^{-1} u(\lambda x)
$$

converges to non-flat area-minimizing cone $K \subset \mathbb{R}^{n+1}$.
$K^{2} \subset \mathbb{R}^{3}$ is a minimal cone, then $K$ must be flat.

## Liouville theorem for Monge-Ampere eq

Consider a convex solution to the equation

$$
\operatorname{det} D^{2} u=1 \text { on } \mathbb{R}^{n}
$$

Example: $u=\frac{1}{2}|x|^{2}$, or in general

$$
u(x)=\frac{1}{2} x^{T} A x+\mathbf{b} \cdot x+c
$$

$A$ : $\mathrm{n} \times \mathrm{n}$ positive matrix with $\operatorname{det} A=1, \mathbf{b}$ : vector, $c$ : constant

$$
D^{2} u=A \quad \Longrightarrow \quad \operatorname{det} D^{2} u=1
$$

Celebrated Liouville theorem in MA equation and affine geometry,

## Theorem (Jörgens '54, Calabi '58, Pogorelov '72)

There is no other solution except convex quadratic polynomials

In other words, the solutions are unique modulo affine transforms

- Jörgens $n=2$, Calabi $n \leq 5$, Pogorelov $n \geq 2$
- Cheng-Yau '86 analytic proof based on affine geometry
- Caffarelli-Y.Li '04 and Y.Li-S.Lu '19 perturbation of RHS

$$
\operatorname{det} D^{2} u=f(x)
$$

$f=1$ outside of compact set, $f$ is $\mathbb{Z}^{n}$-periodic

## Main result

## Theorem (C.-Choi-Kim '21)

Classify all possible solutions to

$$
\operatorname{det} D^{2} u=\left(1+|D u|^{2}\right)^{2-\frac{1}{2 \alpha}} \text { on } \mathbb{R}^{2}
$$

$$
\text { for } 0<\alpha<\frac{1}{4} \text {. }
$$

- $\operatorname{det} D^{2} v=\left(1+|x|^{2}\right)^{\frac{1}{2 \alpha}-2}$ by Legendre transform

$$
v(p)=\sup _{x}[p \cdot x-u(x)]
$$

- $\alpha=\frac{1}{4}$ : affine-critical and $\alpha<\frac{1}{4}$ : sub-affine-critical
- RHS and $\alpha$ come from a geometric context


## Gauss curvature flow

- Let $\Sigma_{t}$ be a 1-parameter family of convex hypersurfaces in $\mathbb{R}^{3}$.
$\Sigma_{t}$ is $\alpha$-Gauss Curvature Flow if the surface moves toward inside with the speed $K^{\alpha}$. Here

$$
K=\lambda_{1} \lambda_{2}=\text { Gaussian curvature at } X \in \Sigma_{t} .
$$

- In other words,

$$
\frac{\partial}{\partial t} X=K^{\alpha} \mathbf{n}
$$

$\mathbf{n}=$ inward unit normal vector at $X \in \Sigma_{t}$

$$
K \approx \operatorname{det} D^{2} u \text { for graph } x_{3}=u\left(x_{1}, x_{2}\right)
$$

A translating soliton is a self-similar solution which moves in constant speed, namely

$$
\Sigma_{t}=\Sigma_{0}+t \mathbf{e}_{3} \quad \text { for } t \in(-\infty, \infty)
$$



In this caes, $\Sigma_{0}$ solves $K^{\alpha}=\left\langle\mathbf{n}, \mathbf{e}_{3}\right\rangle$ and

$$
\operatorname{det} D^{2} u=\left(1+|D u|^{2}\right)^{2-\frac{1}{2 \alpha}}
$$

## Theorem (Andrews '99 - "Fate of Rolling Stones", $n=2, \alpha=1$ )

Every convex closed surface shrinks to a point and becomes round.

- $\alpha=\frac{1}{4}$, the flow converges to an ellipsoid
- Higher dimensions $\alpha>\frac{1}{n+2}$ : Guan-Ni, Andrews-Guan-Ni, Brendle-K.Choi-Daskalopoulos
- $\alpha<\frac{1}{4}$, (generic) flow becomes arbitrary elongated and translating solitons are expected to appear



## Translators to $\alpha$-GCF $\alpha>1 / 2$

$$
\operatorname{det} D^{2} u=\lambda\left(1+|D u|^{2}\right)^{\frac{n+2}{2}-\frac{1}{2 \alpha}} \text { in } \mathbb{R}^{n+1}(\text { speed } \lambda>0) .
$$

## Theorem (J.Urbas '98 '99)

For $\alpha>1 / 2$,

- Every translator is a graph on some convex bounded domain $\Omega \subset \mathbb{R}^{n}$.
- Conversely, for given such an $\Omega \subset \mathbb{R}^{n}$, there is a unique translator which is a complete graph on $\Omega$.

- Speed $\lambda$ is given in terms of the area of $\Omega$ and $\alpha$.


## Translators $\alpha<1 / 2$

- Classification is completely unknown except $\alpha=\frac{1}{n+2}$, affine-critical case
- Rotationally symmetric solution is always entire

Jian-Wang '14 showed

- For $\alpha<\frac{1}{n+1}$, translators are always entire and

$$
|x|^{\alpha} \lesssim u(x) \lesssim|x|^{\beta} \text { for some } 1<\alpha<\beta
$$

- For $\alpha<\frac{1}{2}, \infty$-many non-rotationally symmetric translators exist

Our work shows, for $n=2$ and $\alpha<\frac{1}{n+2}=\frac{1}{4}$,

$$
|x|^{\frac{1}{1-2 \alpha}} \lesssim u(x) \lesssim|x|^{\frac{1}{1-2 \alpha}}
$$

Recall Jörgens' result: upto translations and rotations,

$$
u_{A}(x)=\frac{1}{2}\left(A x_{1}^{2}+A^{-1} x_{2}^{2}\right) \text { for some } A>0
$$

solutions are 1-parameter family.

## Theorem (CCK, $n=2, \frac{1}{9} \leq \alpha<\frac{1}{4}$ )

There is 1-parameter family of translators satisfying
$u_{A}(x)=C_{\alpha}|x|^{\frac{1}{1-2 \alpha}}+A|x|^{\gamma_{\alpha}} \cos (2 \theta)+O\left(|x|^{\gamma_{\alpha}-\epsilon}\right), \quad x=\left(x_{1}, x_{2}\right)$
and there is no other translator (upto rotations and translations).

- Translators are asymptotically round
- $C$ and $\gamma$ depend only on $\alpha$. Moreover, $\gamma \rightarrow 2$ as $\alpha \rightarrow \frac{1}{4}$

$$
r^{\gamma} \cos 2 \theta \rightarrow r^{2} \cos 2 \theta=x_{1}^{2}-x_{2}^{2}
$$

Why does such a difference appear?
Let $u_{0}(x)$ be rotationally symmetric translator

$$
\operatorname{det} D^{2} u_{0}=\left(1+\left|D u_{0}\right|^{2}\right)^{2-\frac{1}{2 \alpha}} .
$$

The linearized equation $L_{u_{0}} w=0$ has solutions (Jacobi fields) $w=r^{\beta} \cos 2 \theta$ and $r^{\beta} \sin 2 \theta$.

- If $\alpha=\frac{1}{4}, \beta=2$
- If $\alpha<\frac{1}{4}, \beta<\frac{1}{1-2 \alpha}$

Other Jacobi fields are $w=r^{\frac{2 \alpha}{1-2 \alpha}} \cos \theta, r^{\frac{2 \alpha}{1-2 \alpha}} \sin \theta, 1$ and so on.

For $\alpha<\frac{1}{9}$, we have more interesting phenomenon


- When $\alpha=1 / 9, w=r^{\frac{1}{1-2 \alpha}} \cos 3 \theta$ is a Jacobi field and asymptotically 3 -fold solution bifurcated from there


## Theorem (CCK Unique self-similar blow-down)

As $\lambda \rightarrow \infty$,

$$
u_{\lambda}(x):=\lambda^{-\frac{1}{1-2 \alpha}} u(\lambda x) \rightarrow|x|^{\frac{1}{1-2 \alpha}} g(\theta)
$$

for some $g(\theta)$. The level curve $\left\{|x|^{\frac{1}{1-2 \alpha}} g(\theta)=1\right\}$ is a shrinking soliton to $\frac{\alpha}{1-\alpha}$-Gauss curvature flow (of curves) in $\mathbb{R}^{2}$.

- $u(x)$ is asymptotic to $r^{\frac{1}{1-2 \alpha}} g(\theta)$ as $|x|=r \rightarrow \infty$
- A closed curve $\Gamma \subset \mathbb{R}^{2}$ is shrinking soliton for $\frac{\alpha}{1-\alpha}$-curve shortening flow if $K^{\frac{\alpha}{1-\alpha}}=\lambda\langle X,-\mathbf{n}\rangle$
- B. Andrews ' 03 classified shrinkers as in previous slide


## Level curves for $\alpha=\frac{1}{4}$ vs $\alpha<\frac{1}{4}$

- If $\alpha=\frac{1}{4}, u(x)=x^{T} A x=r^{2} g(\theta)$ convex paraboloid.
$\{u(x)=l\}$ are homothetic ellipsoids (=shrinker)
- If $\alpha<\frac{1}{4}, u(x)=r^{\frac{1}{1-2 \alpha}} g(\theta)+O\left(r^{\frac{1}{1-2 \alpha}-\epsilon}\right)$
$\{u(x)=l\}$ converges to a shrinker (after rescaling) as $l \rightarrow \infty$


## Steps of proof

For given translator $u(x)$, show the followings
(1) $|x|^{1 / 1-2 \alpha} \lesssim u(x) \lesssim|x|^{1 / 1-2 \alpha}$
(2) $u_{\lambda}(x):=\lambda^{-\frac{1}{1-2 \alpha}} u(\lambda x) \rightarrow|x|^{\frac{1}{1-2 \alpha}} g(\theta)$ along subsequences $\lambda \rightarrow \infty$. Here $g$ is unique upto rotations
(3) $g$ is actually unique (no rotation) and full convergence holds
(4) convergence rate $u(x)=r^{\frac{1}{1-2 \alpha}} g(\theta)+O\left(r^{\frac{1}{1-2 \alpha}-\epsilon}\right), \epsilon>0$
(5) $u=u_{\mathbf{y}_{0}}$ some $\mathbf{y}_{0} \in \mathbb{R}^{K}$. Here, $\left\{u_{\mathbf{y}}\right\}_{\mathbf{y} \in \mathbb{R}^{K}}$ is $K$-param. family of translators (constructed in the existence part) satisfying the asymptotic condition in previous step

## Step 1 and 2 use Daskalopoulos-Savin '08

- showed the homogeneous growth rate $|x|^{\frac{1}{1-2 \alpha}}$ (theory of MA eq) and found a sort of monotonicity formula that is crucial in selfsimilar blow-down

Step 3 uses techniques from Allard-Almgren '81

- uniqueness of tangent cones to minimal surface under some integrability assumption

Step 5 uses a nonlinear Gram-Schmidt process is employed to read off correct 'coordinates' $\mathbf{y}_{0} \in \mathbb{R}^{K}$ by use of Merle-Zaag ODE lemma

To sketch step 5 , assume the simplest case when $u$ is asymptotically round, i.e.

$$
u(x)=c_{1}|x|^{\frac{1}{1-2 \alpha}}\left(1+o\left(|x|^{-\delta}\right)\right) .
$$

The relative error $v(x)=\frac{u(x)-c_{1}|x|^{\frac{1}{1-2 \alpha}}}{c_{1}|x|^{1-2 \alpha}}$ solves

$$
L(v):=r^{2} v_{r r}+c_{2} r v_{r}+c_{3}\left(v+v_{\theta \theta}\right)=\mathcal{N}(v)
$$

with

$$
\mathcal{N}(v) \lesssim\left(|v|+r|D v|+r^{2}\left|D^{2} v\right|\right)^{2} .
$$

By elliptic regularity,

$$
|v|+r|D v|+r^{2}\left|D^{2} v\right|=O\left(r^{-\delta}\right) \text { as } r \rightarrow \infty
$$

making $\mathcal{N}(v)$ negligible compared to $L v$.
$L v=0$ has the kernel (Jacobi fields)

$$
r^{\beta_{j}^{+}} \cos (j \theta), r^{\beta_{j}^{-}} \cos (j \theta), r^{\beta_{j}^{+}} \sin (j \theta), r^{\beta_{j}^{-}} \sin (j \theta)
$$

Roughly speaking,
$\{$ translators $\} \longleftrightarrow\left\{\right.$ Jacobi fields with $\left.\beta \in\left[-\frac{1}{1-2 \alpha}, 0\right)\right\}$.

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\frac{1}{9} \leq \alpha<\frac{1}{4}$ | 1 | X | X | X | $\cdots$ |
| $\frac{1}{16} \leq \alpha<\frac{1}{9}$ | 3 | 2 | X | X | $\cdots$ |
| $\frac{1}{25} \leq \alpha<\frac{1}{16}$ | 5 | 2 | 4 | X | $\cdots$ |
| $\frac{1}{36} \leq \alpha<\frac{1}{25}$ | 7 | 2 | 4 | 6 | $\cdots$ |
| $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$. |

TABLE 1. the number of parameters modulo rigid motions

## Brief idea- nonlinear 1st order ODE system

The eq for $v$ can be rewritten as (with $s=\ln r$ )

$$
\frac{\partial}{\partial s}\left[\begin{array}{c}
v \\
\partial_{s} v
\end{array}\right]=\left[\begin{array}{c}
\partial_{s} v \\
-2 \partial_{s} v-3 v_{\theta \theta}
\end{array}\right]+\left[\begin{array}{c}
0 \\
\mathcal{N}
\end{array}\right]=\mathbf{L}\left[\begin{array}{c}
v \\
\partial_{s} v
\end{array}\right]+\left[\begin{array}{c}
0 \\
\mathcal{N}
\end{array}\right] .
$$

Eigenvectors of $\mathbf{L}$ are

$$
\mathbf{L}\left[\begin{array}{c}
\sin j \theta \\
\beta_{j}^{ \pm} \sin j \theta
\end{array}\right]=\beta_{j}^{ \pm}\left[\begin{array}{c}
\sin j \theta \\
\beta_{j}^{ \pm} \sin j \theta
\end{array}\right]
$$

Express

$$
\left[\begin{array}{c}
v \\
\partial_{s} v
\end{array}\right](s)=\sum \varphi_{c, j}^{ \pm}(s)\left[\begin{array}{c}
\cos j \theta \\
\beta_{j}^{ \pm} \cos j \theta
\end{array}\right]+\varphi_{s, j}^{ \pm}(s)\left[\begin{array}{c}
\sin j \theta \\
\beta_{j}^{ \pm} \sin j \theta
\end{array}\right]
$$

and investigate 1st order ODE system of $\left\{\varphi_{c, j}^{ \pm}(s), \varphi_{s, j}^{ \pm}(s)\right\}$.
$\left\{\varphi_{c, j}^{ \pm}(s), \varphi_{s, j}^{ \pm}(s)\right\}$ solves some 'weakly' coupled first order ODE system since $\mathcal{N}$ is much smaller than $\left(v, v_{s}\right)$.

If $\mathcal{N} \equiv 0$, then $\varphi_{c, j}^{ \pm}(s)=\varphi_{c, j}^{ \pm}(0) e^{\beta_{j}^{ \pm} s}$. So we group eigenspaces into three parts
$\left\{\beta_{j}^{ \pm}>0\right\}$ unstable, $\left\{\beta_{j}^{ \pm}=0\right\}$ neutral,$\left\{\beta_{j}^{ \pm}<0\right\}$ stable

## Theorem (Merle and Zaag ODE Lemma '98)

Let $x(t), y(t)$, and $z(t)$ be nonnegative functions such that

$$
x+y+z \rightarrow 0 \text { as } t \rightarrow \infty
$$

and there is $c_{0}>0$ s.t. for all $\epsilon>0$,

$$
\begin{gathered}
x^{\prime} \geq c_{0} x-\epsilon(y+z) \\
\left|y^{\prime}\right| \leq \epsilon(x+y+z) \\
z^{\prime} \leq-c_{0} z+\epsilon(x+y)
\end{gathered}
$$

for all large time $t>T(\epsilon)$.
Then, as $t \rightarrow \infty$, either $y$ is dominant, $x+z=o(y)$, or $z$ is dominant, $x+y=o(z)$.

Liouville results for ancient MCFs and Ricci flows- Angenent, Daskalopoulos, Sesum, K.Choi, Brendle, Haslhofer, Hershkovits, Naff...

## Theorem (First leading coefficients)

There are $A_{i} \in \mathbb{R}$ such that

$$
v=A_{1} e^{\beta_{K}^{+} s} \cos K \theta+A_{2} e^{\beta_{K}^{+}} \sin K \theta+O\left(e^{\left(\beta_{K}^{+}-\epsilon\right) s}\right)
$$

Since the eq is nonlinear, the next order asymptotic is not dominated by a Jacobi field. However, the difference of two solutions is dominated by a Jacobi field.

Theorem (Finding next coefficients)
If $v_{2}-v_{1}=O\left(e^{\gamma s}\right)$ with $\beta_{N}^{+} \leq \gamma<\beta_{N+1}^{+}<0$ some $N$, then

$$
v_{2}-v_{1}=A_{1} e^{\beta_{N}^{+} s} \cos N \theta+A_{2} e^{\beta_{N}^{+} s} \sin N \theta+O\left(e^{\left(\beta_{N}^{+}-\epsilon\right) s}\right)
$$

We iterate this and find $v-v_{\mathbf{y}_{0}}=o\left(r^{-\frac{1}{1-2 \alpha}}\right) \Rightarrow u \equiv u_{\mathbf{y}_{0}}$.

Further Problems:
To tackle higher dimension $n=3$, we need

- the classification of compact shrinking surfaces to sub-affine-critical GCF in $\mathbb{R}^{3}$
-Some existence was shown by B. Andrews
- the result of Daskalopoulous-Savin on $\mathbb{R}^{3}$

When $n=2, \alpha \in(1 / 4,1 / 2)$,

- $\alpha \in(1 / 4,1 / 3) \Rightarrow$ the solutions are entire, but would generically have different growth rates in different axes.
- $\alpha \in(1 / 3,1 / 2) \Rightarrow$ the solutions will not generically be entire

